

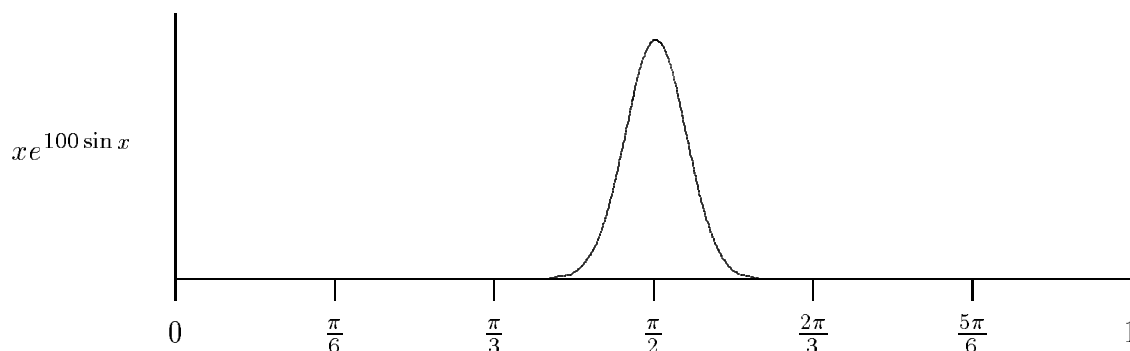
1. Saddle Point Method of Asymptotic Expansion

1.1 THE REAL CASE.

Consider an integral of the form

$$I(A) = \int_{x_1}^{x_2} dx f(x) e^{Ag(x)} \quad (1.1)$$

where f and g are some real functions and A is a parameter. For large values of A the integrand of (1.1) looks like



(in this particular example $f(x) = x, g(x) = \sin x$ and $A = 100$) and the integral is dominated by the contribution of x s near the maximum of g . The width of such maximum is $O(1/\sqrt{A})$, so let us replace x with another integration variable y related to x via

$$x = x_0 + \frac{y}{\sqrt{A}} \quad (1.2)$$

where x_0 is the location of the biggest maximum of g between x_1 and x_2 . Expanding $Ag(x)$ in powers of y , we have

$$Ag(x) = Ag(x_0) + \frac{1}{2}y^2 g''(x_0) + \frac{y^3 g'''(x_0)}{6\sqrt{A}} + \dots \quad (1.3)$$

(the first-derivative term is missing here because x_0 is a maximum of g). Treating this expansion as expansion in powers of $1/\sqrt{A}$ rather than y , we expand the exponential $e^{Ag(x)}$

as

$$e^{Ag(x)} = e^{Ag(x_0)} \cdot e^{y^2 g''(x_0)/2} \cdot \left(1 + \frac{y^3 g'''(x_0)}{6\sqrt{A}} + \frac{y^4 g'''' + 3y^6 (g''')^2}{72A} + \dots \right). \quad (1.4)$$

Similarly, assuming $f(x_0) \neq 0$, we have

$$f(x) = f(x_0) \cdot \left(1 + \frac{y f'(x_0)}{f(x_0)\sqrt{A}} + \frac{y^2 f''(x_0)}{2f(x_0)A} + \dots \right). \quad (1.5)$$

Substituting eqs. (1.4) and (1.5) into (1.1) gives us

$$I(A) = \frac{f(x_0) e^{Ag(x_0)}}{\sqrt{A}} \int_{y_1}^{y_2} dy e^{y^2 g''(x_0)/2} \cdot \left(1 + \sum_{n=1}^{\infty} A^{-n/2} P_n(y) \right), \quad (1.6)$$

where P_n are some polynomial functions of y ; it is easy to show that $P_n(y)$ are odd polynomials for odd n and even polynomials for even n .

In the large A limit $y_1 \rightarrow -\infty$ and $y_2 \rightarrow +\infty$ as $O(\sqrt{A})$ (we assume that the maximum of g occurs strictly between x_1 and x_2 and not at one of the end points). Since the gaussian factor $e^{y^2 g''(x_0)/2}$ decreases very rapidly when $y \rightarrow \pm\infty$ (note that $g''(x_0)$ is negative since x_0 is a maximum of g), extending the integration range of the integral (1.6) to the entire real axis would not make much of an impact on $I(A)$ (the relative mistake in $I(A)$ due to this extension would decrease with A faster than any power of A). Therefore,

$$\begin{aligned} I(A) &\approx \frac{f(x_0) e^{Ag(x_0)}}{\sqrt{A}} \int_{-\infty}^{+\infty} dy e^{y^2 g''(x_0)/2} \cdot \left(1 + \sum_{n=1}^{\infty} A^{-n/2} P_n(y) \right) \\ &= f(x_0) e^{Ag(x_0)} \sqrt{\frac{2\pi}{-Ag''(x_0)}} \times \left(1 + \sum_{n=1}^{\infty} \frac{C_{2n}}{A^n} \right) \end{aligned} \quad (1.7)$$

(all C_{2n-1} vanish because P_{2n-1} are odd polynomials of y). It is a straightforward exercise to work out explicit expressions for the C_{2n} in terms of derivatives of f and g ; for example $C_2 = -f''/4fg'' + f'g'''/8f(g'')^2 + g''''/32(g'')^2 - 5(g''')^2/192(g'')^3$. However, in the interest of brevity, this exercise is left to the reader.

The series in eq. (1.7) usually has zero radius of convergence and thus cannot be summed for any finite value of A . However, partial sums of *asymptotic series* like (1.7) are mathematically guaranteed to have the right asymptotic behavior in the large A limit, that is

$$1 + \sum_{n=1}^{\infty} \frac{C_{2n}}{A^n} = 1 + O(1/A) = 1 + C_2/A + O(1/A^2) = 1 + C_2/A + C_4/A^2 + O(1/A^3) = \dots \quad (1.8)$$

in the strict mathematical sense of $O(1/A^n)$. Thus the precise meaning of eq. (1.7) is

$$\begin{aligned} I(A) &= f(x_0) e^{Ag(x_0)} \sqrt{\frac{2\pi}{-Ag''(x_0)}} \cdot (1 + O(1/A)) \\ &= f(x_0) e^{Ag(x_0)} \sqrt{\frac{2\pi}{-Ag''(x_0)}} \cdot (1 + C_2/A + O(1/A^2)) \\ &= \dots \end{aligned} \quad (1.9)$$

in the large A limit.

1.2 THE COMPLEX CASE.

Now consider the case of complex $f(x)$ and $g(x)$. Again, in the large A limit the integrand is sharply peaked near the maximum of $\text{Reg}(x)$, so we could proceed in exactly the same manner as in the real case. There is however one crucial difference — the maximum of $\text{Reg}(x)$ is not necessarily the stationary point of the phase $\text{Img}(x)$, so we have to add a purely imaginary term $\sqrt{A}yg'(x_0)$ to the expansion (1.3) for the $Ag(x)$. Consequently, the integral (1.6) becomes

$$I(A) = \frac{f(x_0) e^{Ag(x_0)}}{\sqrt{A}} \int dy e^{y^2 g''(x_0)/2} e^{y\sqrt{A}g'(x_0)} \cdot \left(1 + \sum_{n=1}^{\infty} A^{-n/2} P_n(y) \right), \quad (1.10)$$

and the rapidly (in the large A limit) oscillating phase factor $e^{y\sqrt{A}g'(x_0)}$ severely suppresses the asymptotic behavior of the integral. Specifically, the leading term in the expansion now

gives us

$$I(A) \xrightarrow[A \rightarrow \infty]{?} f(x_0) e^{Ag(x_0)} \sqrt{\frac{2\pi}{-Ag''(x_0)}} \cdot \exp\left(-Ag'^2(x_0)/g''(x_0)\right), \quad (1.11)$$

and the last factor here is very small because the real part of $g'^2(x_0)/g''(x_0)$ is always positive.

Thus the maxima of $\text{Re}g(x)$ do not contribute at full strength unless such a maximum also happen to be a stationary point of the phase $\text{Im}g(x)$. The suppression is so strong that the region around a maximum of $\text{Re}g$ that is not a stationary point of the phase may no longer dominate the large A asymptotic behavior of the integral. Thus a different approach is needed in the complex case. Fortunately, such an approach is easy to deduce from the proper way to complexify the real integral (1.1).

The proper complexification of (1.1) is a contour integral

$$I(A) = \int_{\Gamma} dz f(z) e^{Ag(z)}, \quad (1.12)$$

where $f(z)$ and $g(z)$ are complex analytic functions and Γ is a contour in the complex plane. A fundamental theorem of complex analysis states that contour integrals of analytic functions are invariant under any continuous deformation of the contour that does not affect its end points (if any) and does not drag contour over any singularities of the integrand. Thus for the problem at hand we deform the contour until the maximum of $\text{Re}g$ along the contour is also a stationary point of the phase $\text{Im}g$. Notice that such deformation may turn a real interval from x_1 to x_2 into a non-real contour in the complex plane, which may seem like making the problem even more complex (in both senses of the word) than it is, but does in fact lead to an easily obtainable large A asymptotics.

The points in the complex plane where a maximum of $\text{Re}g$ (along some contour) coincides with a stationary point of the phase $\text{Im}g$ are the zeros of the complex derivative $g'(z)$. Near such a point $\text{Re}g(z)$ looks like a saddle or the top of a mountain pass — it has a maximum along some directions in the complex plane and a minimum along other directions — hence the two names for the asymptotic method described here: *the saddle point method* or *the*

mountain pass method. The mountain pass analogy is particularly apt, for a properly routed contour not only goes through a zero of g' , but crosses that zero in the manner of a highway crossing a mountain pass, by starting in a valley (of low $\text{Re}g$), going up till it reaches the top of the pass, then going down into another valley. Only a mountain goat would think of a pass as a low point on a trail from one hill to another, and you should not think like a goat when computing integrals!

Once you have the right contour Γ , obtaining the large A asymptotics of the integral (1.12) becomes analogous to the real case. First, we change the integration variable from z to a new complex variable y related to z via

$$z = z_0 + \frac{\eta y}{\sqrt{A}}, \quad (1.13)$$

where z_0 is a zero of $g'(z)$ and η is a unimodular complex number. Second, we expand the integrand of (1.12) into powers of $1/\sqrt{A}$ in the same manner as we did in the real case; this gives us

$$I(A) = \frac{\eta f(z_0) e^{Ag(z_0)}}{\sqrt{A}} \int_{\Gamma'} dy e^{y^2 \eta^2 g''(z_0)/2} \cdot \left(1 + \sum_{n=1}^{\infty} \eta^{-n} A^{-n/2} P_n(y) \right), \quad (1.14)$$

where Γ' is the integration contour in the y plane. Γ' always crosses the point $y = 0$, but the direction of that crossing depends on η ; to simplify our arguments, let us choose the η that would make Γ' tangent to the real axis at $y = 0$ (more specifically, dy along Γ' should be real and positive when $y = 0$). As A grows large, all points on the contour Γ' scale as \sqrt{A} , so if it is tangent to the real axis for finite A , in the $A \rightarrow \infty$ limit Γ' simply becomes the real axis with some appendages at infinity. Similar to the real case, contributions of very large y do not affect the asymptotic large A behavior of the integral (1.14); hence

$$\begin{aligned} I(A) &\approx \frac{\eta f(z_0) e^{Ag(z_0)}}{\sqrt{A}} \int_{-\infty}^{+\infty} dy e^{y^2 \eta^2 g''(z_0)/2} \cdot \left(1 + \sum_{n=1}^{\infty} \eta^{-n} A^{-n/2} P_n(y) \right) \\ &= \sqrt{\frac{2\pi}{A}} \exp(Ag(z_0)) \cdot \frac{\eta f(z_0)}{\sqrt{-\eta^2 g''(z_0)}} \cdot (1 + O(1/A)), \end{aligned} \quad (1.15)$$

in complete analogy to the real formula (1.9). (The gaussian integral on the first line of

this formula is always convergent because the way we chose η assures that $\eta^2 g''(z_0)$ has negative real part whenever the contour Γ in the z plane crosses the z_0 point like a mountain highway and not like a mountain goat trail). Note that the η parameter in the formula (1.15) essentially cancels itself out, except that it helps determine the sign of the complex square root $\sqrt{-\eta^2 g''(z_0)}$ — its real part should be positive.

Although formulæ (1.9) and (1.15) differ very little, there is one important difference between large A asymptotics of real and complex integrals $I(A)$. The asymptotics of a real integral (1.1) is always dominated by the global maximum of $g(x)$ *within the integration range*, which can be either the biggest local maximum x_0 strictly within the range, or one of the end points of that range (in which case eq. (1.9) does not apply). Local maxima of $g(x)$ *outside* the integration range of (1.1) never play any role in the asymptotic expansion even if they are bigger than any maximum within the range.

For the complex integrals (1.12), determining which of the saddle points of $g(z)$ in the complex plane dominates the integral's asymptotics is not so straightforward. Given the freedom to deform the integration contour Γ , one cannot simply say that a saddle point z_0 is “within the integration range” while another saddle point is “outside the integration range” since Γ can always be deformed to cross any point we like. Usually, the general direction of the original contour and the phases of g'' at saddle points which control the directions in which those saddle points should be traversed give sufficient clues to determine which saddle point is dominant and how to deform the contour to go through it. However, such determination is somewhat of a black art best explained on specific examples; one such example — the asymptotic behavior of Airy functions — shall be discussed in the next chapter.

2. Airy Functions

2.1 CONSTRUCTION.

Airy functions Ai and Bi are solutions of the linear differential equation

$$\Psi''(z) - z\Psi(z) = 0, \quad (2.1)$$

which is a scale-invariant form of the Schrodinger equation for a quantum particle subject to a constant force, *i.e.*, linear potential. The relation between z and the particle's coordinate x is $z = \sqrt[3]{2mF/\hbar^2} \cdot (x - x_0)$, where x_0 is the classical turning point.

For Bessel functions experts the easiest way to solve the equation (2.1) is to substitute

$$z = \frac{2i}{3}y^{3/2}, \quad \Psi(z) = y^{1/3}J(y). \quad (2.2)$$

In terms of $J(y)$ equation (2.1) becomes

$$J''(y) + \frac{1}{y}J'(y) + \left(1 - \frac{1}{9y^2}\right)J(y); \quad (2.3)$$

this is the Bessel equation of the order $1/3$, so $J(y)$ is a linear combination of the Bessel functions $J_{+1/3}(y)$ and $J_{-1/3}(y)$.

However, it is more instructive to solve the equation (2.1) in a different way. Let us perform a Laplace-like transform and look for a solution $\Psi(z)$ in the form of a contour integral

$$\Psi(z) = \int_{\Gamma} dt e^{tz} \Phi(t); \quad (2.4)$$

here Γ is some z -independent contour in the complex t plane and $\Phi(t)$ is an analytic function of t that does not have any singularities on the contour Γ . With these assumptions, the second

derivative $\Psi''(z)$ is related to $t^2\Phi(t)$ via

$$\Psi''(z) = \int_{\Gamma} dt e^{tz} t^2 \Phi(t). \quad (2.5)$$

On the other hand, $z\Psi(z)$ is related to the first derivative of $\Phi(t)$ via

$$z\Psi(z) = [e^{tz}\Phi(t)]_{\delta\Gamma} - \int_{\Gamma} dt e^{tz} \Phi'(t) \quad (2.6)$$

(to prove (2.6), substitute $ze^{tz} = \partial e^{tz}/\partial t$ and integrate by parts). Therefore, in terms of $\Phi(t)$, the second order eq. (2.1) is equivalent to a first order equation

$$t^2\Phi(t) + \Phi'(t) = 0, \quad (2.7)$$

plus a boundary condition

$$e^{tz}\Phi(t) = 0 \quad \text{on the boundary of the contour } \Gamma. \quad (2.8)$$

The general solution of the equation (2.7) is

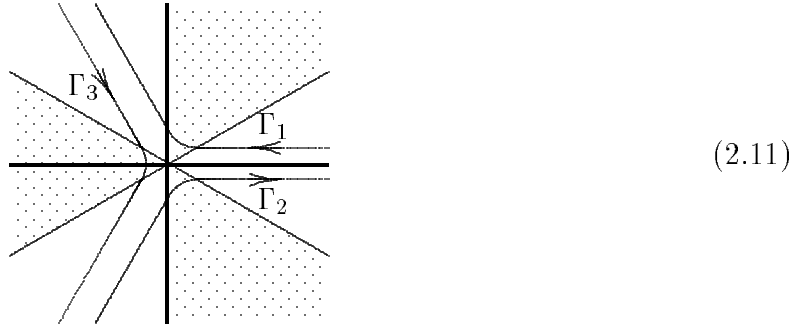
$$\Phi(t) = C \exp(-t^3/3), \quad (2.9)$$

where C is a constant; therefore, we have solved the Airy equation (2.1) in terms of the contour integral

$$\Psi(z) = C \int_{\Gamma} dt \exp(tz - \frac{1}{3}t^3). \quad (2.10)$$

So far I haven't specified the integration contour Γ . Since the integrand of eq. (2.10) has no singularities for any finite t , only the end points of the contour would affect the integral; in particular, any closed Γ would lead to the trivial solution $\Psi(z) \equiv 0$. On the other hand, an open Γ with finite end points would violate the boundary condition (2.8). Hence, both end

points of the contour Γ must be at the complex ∞ , and the directions in which the two ends of the contour approach the ∞ would completely determine the integral (2.10) (the latter follows from the lack of finite singularities of the integrand). Those directions of approach are controlled by two considerations: First, one should approach the infinity along directions in which the integrand decreases rather than increases; for the problem at hand, this allows angles of approach between $-\pi/6$ and $+\pi/6$, between $+\pi/2$ and $+5\pi/6$, and between $-5\pi/6$ and $-\pi/2$, that is, within three white sectors on the following diagram:



The second consideration is that all approaches within the same sector are equivalent; consequently, the two ends of the contour must belong to different sectors. These two considerations give us a choice of three contours — Γ_1 , Γ_2 and Γ_3 on figure (2.11) — corresponding to three different solutions $\Psi_1(z)$, $\Psi_2(z)$ and $\Psi_3(z)$ of the Airy equation (2.1). Since the combined contour $\Gamma_1 + \Gamma_2 + \Gamma_3$ is shrinkable, it follows that $\Psi_1(z) + \Psi_2(z) + \Psi_3(z) \equiv 0$, so only two of the solutions are independent. The Airy functions Ai and Bi are the two independent solutions

$$\begin{aligned}
 Ai(z) &= iC \int_{\Gamma_3} dt \exp\left(tz - \frac{1}{3}t^3\right), \\
 Bi(z) &= C \int_{\Gamma_2 - \Gamma_1} dt \exp\left(tz - \frac{1}{3}t^3\right)
 \end{aligned}
 \tag{2.12}$$

that are real for real z . (The integral over $\Gamma_2 - \Gamma_1$ is the integral over Γ_2 , plus the integral over $-\Gamma_1$, the latter being Γ_1 traversed in the direction opposite to the arrow on figure (2.11).)

2.2 ASYMPTOTICS

For the purpose of matching WKB solutions on two sides of a classical turning point we need to know the asymptotic behaviors of the Airy functions for large real z , both positive and negative. The easiest way to obtain this information is to use the saddle point method described in the previous chapter. Although the integrals in eq. (2.12) do not have the exact form (1.12), changing the integration variable from t to $\tau \equiv t/\sqrt{|z|}$ brings them to the desired form:

$$\begin{aligned} Ai(z) &= iC|z|^{1/2} \int_{\Gamma_3} d\tau \exp\left(|z|^{3/2}\left(\frac{z}{|z|}\tau - \frac{1}{3}\tau^3\right)\right), \\ Bi(z) &= C|z|^{1/2} \int_{\Gamma_2-\Gamma_1} d\tau \exp\left(|z|^{3/2}\left(\frac{z}{|z|}\tau - \frac{1}{3}\tau^3\right)\right) \end{aligned} \quad (2.13)$$

(the contours $\Gamma_{1,2,3}$ are essentially scale invariant and hence can be used without change in both t and τ planes).

For positive z , we have $g(\tau) = \tau - \tau^3/3$ which has saddle points at $\tau = \pm 1$. The positive saddle point at $\tau = +1$ has a higher value of $g(\tau)$ than the negative saddle point ($g(\tau = +1) = +\frac{2}{3}$ while $g(\tau = -1) = -\frac{2}{3}$), so it seems to be dominant. This dominance however would only work for contours that traverse that point in the mountain-pass-like fashion; given $g''(\tau = +1) = -2$, this means within $\pi/4$ of the horizontal axis. A quick look at figure (2.11) shows that contour deformation that would make Γ traverse the point $\tau = +1$ horizontally is an easy thing to do for $\Gamma = \Gamma_2$ or $\Gamma = -\Gamma_1$ ($\eta = +1$ in both cases) but is a very unnatural thing to do to the Γ_3 contour. Hence, as $z \rightarrow +\infty$, the *irregular Airy function* Bi behaves like

$$Bi(z) = 2 \cdot \frac{\sqrt{2\pi}C z^{1/2}}{\sqrt{2z^{3/2}}} e^{\frac{2}{3}z^{3/2}} (1 + O(z^{-3/2})) = \frac{2\sqrt{\pi}C}{z^{1/4}} e^{\frac{2}{3}z^{3/2}} (1 + O(z^{-3/2})) \quad (2.14)$$

(the factor of 2 is due to two contours Γ_2 and $-\Gamma_1$ contributing to Bi), while the asymptotics of the *regular Airy function* Ai is controlled by the other saddle point $\tau = -1$. At that saddle point $g''(\tau = -1) = +2$, so we want the contour to traverse it in a direction within $\pi/4$ of the

vertical axis. Given the general downward direction of the Γ_3 contour, this suggests $\eta = -i$ for the deformed contour that crosses $\tau = -1$, so the regular Airy function looks like

$$Ai(z) = \frac{\sqrt{2\pi} i C z^{1/2}}{i\sqrt{2} z^{3/2}} e^{-\frac{2}{3} z^{3/2}} (1 + O(z^{-3/2})) = \frac{\sqrt{\pi} C}{z^{1/4}} e^{-\frac{2}{3} z^{3/2}} (1 + O(z^{-3/2})) \quad (2.15)$$

for large positive z .

For negative z , $g(\tau) = -\tau - \tau^3/3$ and the saddle points are at $\tau = \pm i$. Both saddle points have the same $\text{Reg}(\tau)$, namely zero, so we expect the two points to be co-dominant for both Ai and Bi . The second derivative $g''(\tau = \pm i) = \mp 2i$, so the mountain-path-like directions are NW to SE or SE to NW at $\tau = +i$ and SW to NE or NE to SW at $\tau = -i$. Again, we use the general direction of the contours on the diagram (2.11) to decide that the deformed Γ_3 should traverse the upper saddle point ($\tau = +i$) in the NW to SE direction ($\eta = e^{-\pi i/4}$) and the lower saddle point ($\tau = -i$) from NE to SW ($\eta = e^{-3\pi i/4}$). Hence, using the general asymptotic formula (1.15), we obtain

$$\begin{aligned} Ai(z) &= \frac{\sqrt{2\pi} i C |z|^{1/2}}{\sqrt{2} |z|^{3/2}} \left(e^{-\pi i/4} e^{-\frac{2}{3} i |z|^{3/2}} + e^{-3\pi i/4} e^{+\frac{2}{3} i |z|^{3/2}} + O(|z|^{-3/2}) \right) \\ &= \frac{2\sqrt{\pi} C}{|z|^{1/4}} \left(\cos\left(-\frac{\pi}{4} + \frac{2}{3} |z|^{3/2}\right) + O(|z|^{3/2}) \right) \end{aligned} \quad (2.16)$$

for the asymptotic behavior of the regular Airy function at large negative z . The irregular Airy function can be studied in the same way: It is plain to see that the deformed Γ_2 contour should traverse only the $\tau = -i$ saddle point in the SW to NE direction ($\eta = e^{+\pi i/4}$) while the deformed $-\Gamma_1$ contour should traverse only the $\tau = +i$ saddle point in the direction NW to SE ($\eta = e^{-\pi i/4}$). Therefore, for large negative z ,

$$\begin{aligned} Bi(z) &= \frac{\sqrt{2\pi} C |z|^{1/2}}{\sqrt{2} |z|^{3/2}} \left(e^{-\pi i/4} e^{-\frac{2}{3} i |z|^{3/2}} + e^{+\pi i/4} e^{+\frac{2}{3} i |z|^{3/2}} + O(|z|^{-3/2}) \right) \\ &= \frac{2\sqrt{\pi} C}{|z|^{1/4}} \left(\cos\left(+\frac{\pi}{4} + \frac{2}{3} |z|^{3/2}\right) + O(|z|^{3/2}) \right). \end{aligned} \quad (2.17)$$

Quantum-Mechanical implications of the Airy function's asymptotic behavior were discussed in class. Here is the summary: Consider a classical turning point — $V(x) < E$ for $x < x_0$ but $V(x) > E$ for $x > x_0$. If the potential $V(x)$ allows for the WKB approximation to be used both on the classically allowed side $x < x_0$ and on the classically forbidden side $x > x_0$ and is sufficiently smooth near x_0 , then the WKB solution on the two sides of the turning point should be matched as follows: The solution that looks like

$$\Psi_1(x) \approx \frac{C}{\sqrt{\kappa(x)}} \exp\left(-\int_{x_0}^x dx' \kappa(x')\right) \quad (2.18)$$

on the classically forbidden side becomes

$$\Psi_1(x) \approx \frac{2C}{\sqrt{k(x)}} \cos\left(-\frac{\pi}{4} + \int_x^{x_0} dx' k(x')\right) \quad (2.19)$$

on the classically allowed side. The other solution looks like

$$\Psi_2(x) \approx \frac{C}{\sqrt{\kappa(x)}} \exp\left(+\int_{x_0}^x dx' \kappa(x')\right) \quad (2.20)$$

on the classically forbidden side and becomes

$$\Psi_2(x) \approx \frac{C}{\sqrt{k(x)}} \cos\left(+\frac{\pi}{4} + \int_x^{x_0} dx' k(x')\right) \quad (2.21)$$

on the classically allowed side.