

Lorentz Invariance in Wave Equations

(1)

What does it mean for a wave equation to be "relativistically invariant"??

Lagrangian formulation of field theory makes it easy to discuss Lorentz invariance:

\mathcal{L} is a scalar.

{ If boosts leave \mathcal{L} unchanged, boosts of extremum will be another extremum. Hence E.o.M. will be unchanged!! }

Consider $k=6$ field.

$$\boxed{x^\mu \rightarrow x'^\mu = \Lambda^\mu_\nu x^\nu}$$

↑
4x4 matrix

Lorentz
transformation

$$\text{So } x = \Lambda x_0$$

$$\underline{\underline{\phi(x) \rightarrow \phi'(x) = \phi(\Lambda^{-1}x)}}$$

{ transformed field evaluated at boosted point, x , is same as original field at value before boosting. }

Recall $\mathcal{L} = \frac{1}{2} (\partial_\mu \phi)^2 - \frac{1}{2} m^2 \phi^2$

ϕ^2 transforms as ϕ (only argument transforms)

$$\partial_\mu \phi(x) \rightarrow \partial_\mu (\phi'(x)) = (\Lambda^{-1})^\nu{}_\mu (\partial_\nu \phi)(\Lambda^{-1}x)$$

\uparrow \uparrow \uparrow \uparrow
 x x x_0 x_0

$$\left\{ \begin{array}{l} \text{As } g^{\mu\nu} \text{ is Lorentz Invariant,} \\ (\Lambda^{-1})^\rho{}_\mu (\Lambda^{-1})^\sigma{}_\nu g^{\mu\nu} = g^{\rho\sigma} \\ \text{w/ } (\Lambda^{-1})^\mu{}_\nu = \Lambda_\nu{}^\mu \end{array} \right\}$$

\therefore

$$\begin{aligned} (\partial_\mu \phi(x))^2 &\rightarrow g^{\mu\nu} (\partial_\mu (\phi'(x))) (\partial_\nu (\phi'(x))) \\ &= g^{\mu\nu} [(\Lambda^{-1})^\rho{}_\mu \partial_\rho \phi] [(\Lambda^{-1})^\sigma{}_\nu \partial_\sigma \phi] (\Lambda^{-1}x) \\ &= g^{\rho\sigma} (\partial_\rho \phi) (\partial_\sigma \phi) (\Lambda^{-1}x) \\ &= (\partial_\mu \phi(\Lambda^{-1}x))^2 \end{aligned}$$

So $\mathcal{L}(x) \rightarrow \mathcal{L}(\Lambda^{-1}x)$

$\therefore \mathcal{L}$ is a SCALAR \Rightarrow

The action S is a scalar

$$S = \int d^4x \mathcal{L}(x)$$

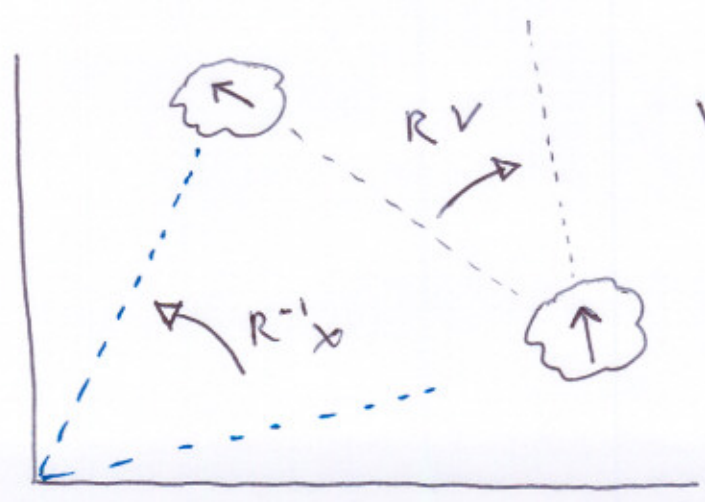
Straightforward to show that E.O.14 is invariant.

Transformation law for a scalar is simplest possible law for a field.

What about vector field $V^\mu(x)$??
(like GEM vector potential)

$$V^\mu(x) \rightarrow \Lambda^\mu_\nu V^\nu(\Lambda^{-1}x)$$

e.g. 3-d rotations



$$V^i(x) \rightarrow R^{ij} V^j(R^{-1}x)$$

Can do some for tensor fields

$$\underline{T}^{\mu\nu} \quad \text{and} \quad \underline{M}^{\mu\nu\dots\sigma\rho}$$

⇒ Large class of Lorentz invariant equations

But there are still more ...

Consider linear transformation on N -component field:

$$\underline{\Phi}_a(x) \quad a = 1, \dots, N$$

Under Lorentz transformation,

$$\underline{\Phi}_a(x) \rightarrow M_{ab}(\Lambda) \underline{\Phi}_b(\Lambda^{-1}x)$$

↑
 $N \times N$ matrix

Suppress for a moment the change in

field argument: $\underline{\Phi} \rightarrow M(\Lambda) \underline{\Phi}$

⑩ What are possible allowed forms for $M(\Lambda)$??

Consider two successive transformations:

$$\underline{\psi} \rightarrow M(\Lambda') M(\Lambda) \underline{\psi} = M(\Lambda'') \underline{\psi}$$

↑ GROUP PROPERTY

for $\Lambda'' = \Lambda' \Lambda$

The M form N -dimensional REPRESENTATION
of the Lorentz group ($SU(2) \times SU(2)$)

Rephrase ⑩:

What are the finite-dimensional matrix
representations of the Lorentz group?

First consider the subgroup of rotations

Remember: with spin quantum # s

$$N = 2s + 1$$

(e.g. If $s = \frac{1}{2}$ (\uparrow or \downarrow) $N = 2$ ✓)

Let's consider $S = \frac{1}{2}$ in some more detail;

Matrices of this representation are:

$$U = e^{-i \theta_i \sigma_i / 2}$$

(in $SU(2)$)
(Rem: $\det = 1$)

θ_i : 3 arbitrary parameters

σ_i : Pauli matrices

Lie algebra ?? "General" Rotations

$$[J_i, J_j] = i \epsilon_{ijk} J_k$$

$$R = e^{-i \theta_i J_i}$$

Similar for Boosts

$$[K_i, K_j] = -i \epsilon_{ijk} J_k$$

etc.

$$B = e^{-i \theta_i K_i}$$

How do we put J_i and K_i together
in relativistic notation ??

Recall that J_i is ANGULAR MOMENTUM

$$J_i = \epsilon_{ijk} x_j p_k = -i \epsilon_{ijk} x_j \nabla_k$$

(or $\vec{J} = \vec{x} \times \vec{p}$)

Define $J_{mn} \equiv \epsilon_{mni} J_i = -i \epsilon_{mni} \epsilon_{ijk} x_j \nabla_k$
 $= -i (\delta_{mj} \delta_{nk} - \delta_{mk} \delta_{nj}) x_j \nabla_k$

2) $J_{mn} = -i (x_m p_n - x_n p_m)$

Now generalize to 4-d :

$$J^{\mu\nu} = i (x^\mu \partial^\nu - x^\nu \partial^\mu)$$

$$[J^{\mu\nu}, J^{\rho\sigma}] = i (g^{\nu\rho} J^{\mu\sigma} - g^{\mu\rho} J^{\nu\sigma} - g^{\rho\sigma} J^{\mu\nu} + g^{\mu\sigma} J^{\nu\rho})$$

→
(pain + suffering)

Algebra of (homogeneous) Lorentz group

Can check :

$$J_{\mu\nu} = \begin{cases} J_{ij} = -J_{ji} = \epsilon_{ijk} J_k \\ J_{i0} = -J_{0i} = -K_i \end{cases}$$

Now say $\underline{w_{0i} = -w_{i0} = \beta}$

$$\Rightarrow V \rightarrow \begin{pmatrix} 1 & \beta & 0 & 0 \\ \beta & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} V \quad (\text{Boost in } x\text{-direction})$$

For homogeneous Lorentz group we have considered Boosts and Rotations:

$$x^{\mu'} = \Lambda^{\mu}_{\nu} x^{\nu} + a^{\mu}$$

now include time + space translations

inhomogeneous Lorentz group

or

Poincaré Group

$$P_{\mu} = i \frac{\partial}{\partial x^{\mu}}$$

Energy - Momentum

Adds 4 generators to Lorentz group:

10 total generators

$$[J^{\mu\nu}, J^{\rho\sigma}] = i(g^{\nu\rho}J^{\mu\sigma} - g^{\mu\rho}J^{\nu\sigma} - g^{\nu\sigma}J^{\mu\rho} + g^{\mu\sigma}J^{\nu\rho})$$

$$[P_\mu, J_{\rho\sigma}] = i(g_{\mu\rho}P_\sigma - g_{\mu\sigma}P_\rho)$$

$$[P_\mu, P_\nu] = 0$$

Algebra of Poincaré group

- J_i and P_i commute w/ $H = P_0$ but K_i does not!
- translations in different directions commute.

In some sense a discussion of the representations of the Poincaré group is a logical starting point for Q.F.T.

The Dirac Equations

ROTATIONS:

$$R = e^{-i\theta_i J_i}$$

BOOSTS:

$$B = e^{-i\theta_i K_i}$$

$$\Lambda = e^{-i/2 \omega_{\mu\nu} J^{\mu\nu}}$$

$SU(2) \times SU(2)$
or
 $(SO(3,1))$

We are interested in representations of the Poincaré group corresponding to fields of spin $\frac{1}{2}$.

Dirac's trick:

Suppose we have $n \times n$ matrices γ^μ which satisfies:

$$\{\gamma^\mu, \gamma^\nu\} = \gamma^\mu \gamma^\nu + \gamma^\nu \gamma^\mu = 2g^{\mu\nu} \mathbb{1}$$

$\mathbb{1}$
 $n \times n$

(note: n is arbitrary - not necessarily 4-D dimension)

Now define:

$$S^{\mu\nu} = \frac{i}{4} [\gamma^\mu, \gamma^\nu]$$

Commutator??

Can show:

$$[S^{\mu\nu}, S^{\rho\sigma}] = i (g^{\nu\rho} S^{\mu\sigma} - S^{\nu\sigma} g^{\mu\rho} - g^{\nu\sigma} S^{\mu\rho} + S^{\mu\sigma} g^{\nu\rho})$$

Satisfies Lorentz group algebra!!
(for any n)

Consider $n = d = 3$ Euclidean space

$$g^{\mu\nu} = \begin{pmatrix} 1 & & 0 \\ & 1 & \\ 0 & & 1 \end{pmatrix}$$

Sg $\gamma^k = i \sigma^k$
 \uparrow CONVENTION!

$$\{\gamma^k, \gamma^\lambda\} = \downarrow \{\sigma^k, \sigma^\lambda\} = -2 \delta^{k\lambda} \checkmark$$

then $S^{ij} = \frac{-i}{4} [\sigma^i, \sigma^j] = \frac{1}{2} \underline{\epsilon^{ijk} \sigma^k}$

Matching $\Rightarrow J^k = \frac{\sigma^k}{2}$

2-d representation of rotation group $SU(2)$

Now consider a representation of γ^m for $d=4$ Minkowski space.

$n = ??$

must be at least $n=4$ i.e. 4×4

Only need 1 explicit representation as < 4 others are unitarily equivalent.

Weyl or Chiral Representation

$\gamma^0 = \begin{pmatrix} 0 & \mathbb{1}_{2 \times 2} \\ \mathbb{1}_{2 \times 2} & 0 \end{pmatrix} \quad \gamma^i = \begin{pmatrix} 0 & \sigma^i \\ -\sigma^i & 0 \end{pmatrix}$

\uparrow 2×2 blocks \uparrow

e.g. $\gamma^0 \gamma^i = \begin{pmatrix} -\sigma^i & 0 \\ 0 & \sigma^i \end{pmatrix} \quad \gamma^i \gamma^0 = \begin{pmatrix} \sigma^i & 0 \\ 0 & -\sigma^i \end{pmatrix}$
 $\{ \gamma^0, \gamma^i \} = 0$

$$\left\{ \gamma^0 \gamma^0 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \quad \{ \gamma^0, \gamma^0 \} = 2 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \right\}$$

Recall that:

$$K^i = S^{0i} = \frac{i}{4} [\gamma^0, \gamma^i] = -\frac{i}{2} \begin{pmatrix} \sigma^i & 0 \\ 0 & -\sigma^i \end{pmatrix}$$

(Not Hermitian, boosts not unitary)

$$S^{ij} = \frac{i}{4} [\gamma^i, \gamma^j] = \frac{1}{2} \epsilon^{ijk} \begin{pmatrix} \sigma^k & 0 \\ 0 & \sigma^k \end{pmatrix} \equiv \frac{1}{2} \epsilon^{ijk} \Sigma^k$$

$$J^i = \Sigma_{\frac{1}{2}}^i = \frac{1}{2} \begin{pmatrix} \sigma^i & 0 \\ 0 & \sigma^i \end{pmatrix}$$

Note:

$$A^i = \frac{1}{2} (J^i + iK^i) = \frac{1}{4} \begin{pmatrix} 2\sigma^i & 0 \\ 0 & 0 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} \sigma^i & 0 \\ 0 & 0 \end{pmatrix}$$

$$B^i = \frac{1}{2} \begin{pmatrix} 0 & 0 \\ 0 & \sigma^i \end{pmatrix}$$

$$[A, A] = A$$

$$[B, B] = B$$

$$[B, A] = 0$$

two independent

$SU(2)$'s

i.e. $SU(2) \times SU(2)$

A 4-component field ψ that transforms in this representation (w/ K_i and J_i) is called a Dirac spinor